

High Altitude Java

The software behind an ESA-sponsored airborne imaging spectrometer

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Netcetera Zurich

7640

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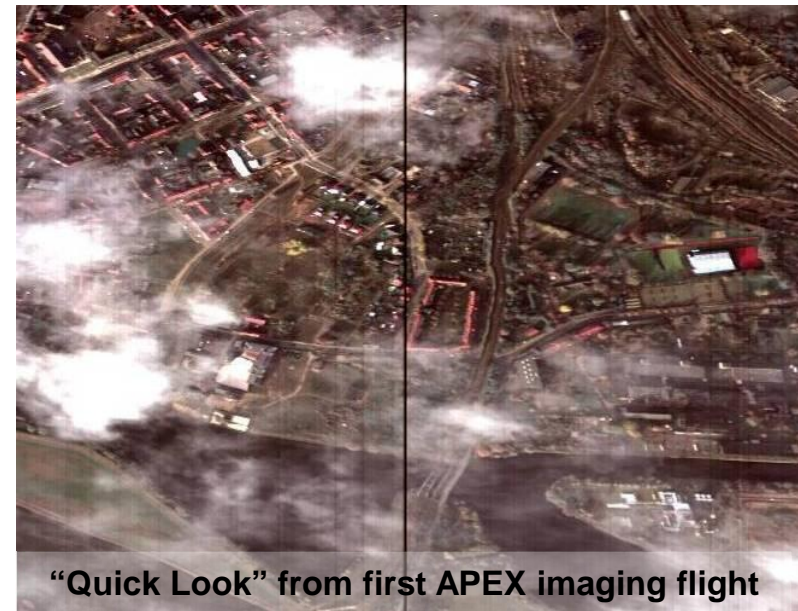
Airborne Prism EXperiment

> The Mission

- Airborne earth-observing “camera”
(pushbroom imaging spectrometer)
~500 bands instead of 3 (red, green, blue)

> Selected Software

- Data Acquisition/Control/Monitoring
Flight plan triggered camera control
Imagery/Positional/Calibration/Environmental data
Near real-time “waterfall image” monitoring
- Offline processing
Instrument calibration support (Seasonal)
Radiometric/spatial correction (Per campaign)
Parametric ortho-rectification (Per campaign)
Atmospheric correction (Per campaign)



“Quick Look” from first APEX imaging flight

The Mission

Who: the APEX team



ESA Team

PRODEX
Technical Officer
Hilde Schroeven-
Deuceuniinck

**Instrument Manager &
Detector Development**
Gerd Ulbrich &
Roland Meynart

Contracts Officer
Ulrich Sterzl

Scientific Advisor
Jens Nieke



Science Team

Principal Investigator
Michael Schaepman

Project Manager
Edoardo Alberti

Calibration Scientist
Francesco Dell'Endice

PAF Scientist
Andreas Hüni

Processing Scientist
Daniel Schläpfer

Scientific Advisor
Klaus Itten



Operations Team

Co-Investigator
Koen Meuleman

**Flight
Operations**
Bart Bomans

Processing Operations
Jan Biesemans

Operator
Johan Mijndonckx



Industrial Team

Industrial Prime
Integration and systems
RUAG AG

Optical Subsystem
OIP Sensor Systems

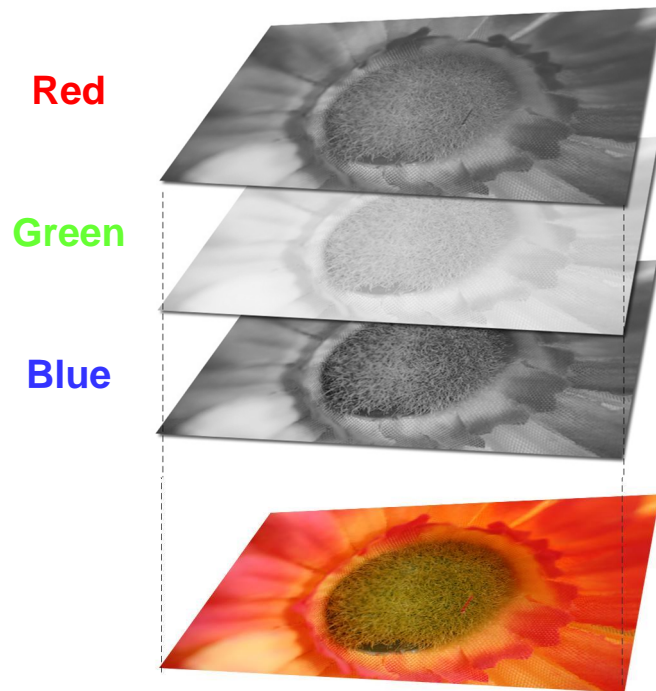
Electronic Subsystem
Netcetera AG

SWIR Detectors
Sofradir

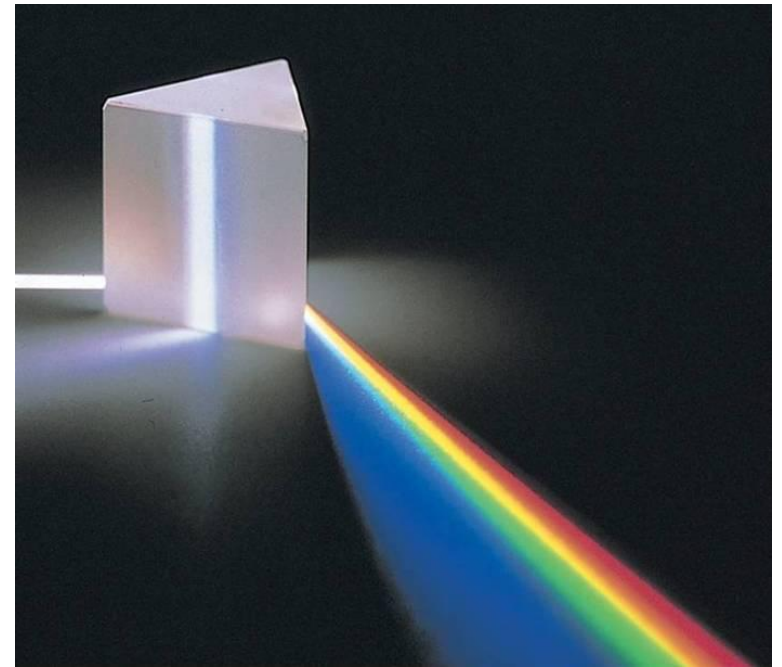
Calibration Home Base
DLR

What: imaging spectroscopy

simultaneous acquisition of spatially *coregistered images*, in *many narrow, spectrally contiguous bands*, measured in *calibrated radiance units*



Digital Camera: 3 bands (red,green,blue)



Imaging spectrometer: 100s bands

What: visualizing “non-visible” wavelengths...



← ultraviolet

visible (blue, green, red)

→ infrared



Photos: Austin Richards, *Alien Vision*, ISBN: 0819441422

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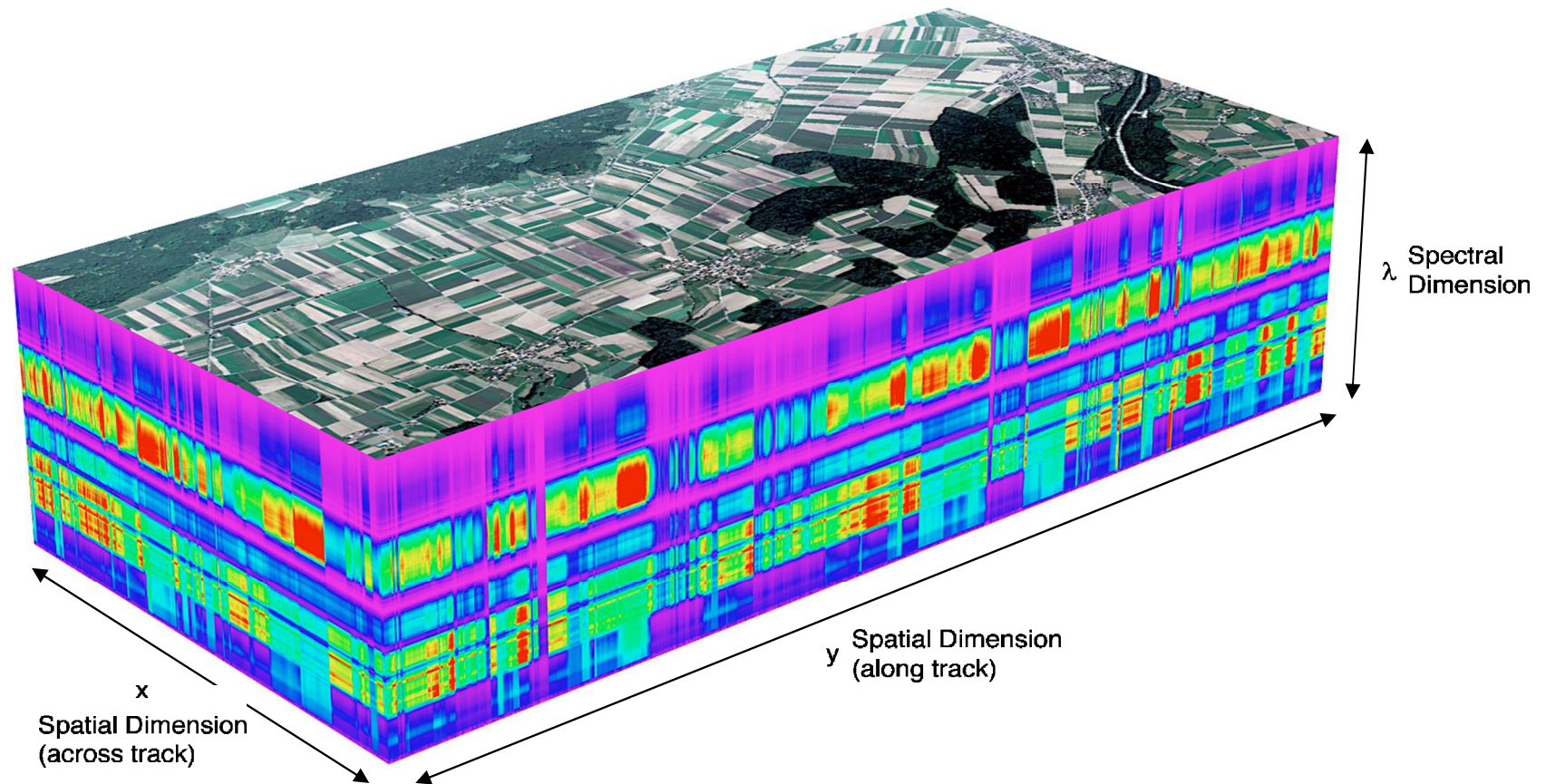
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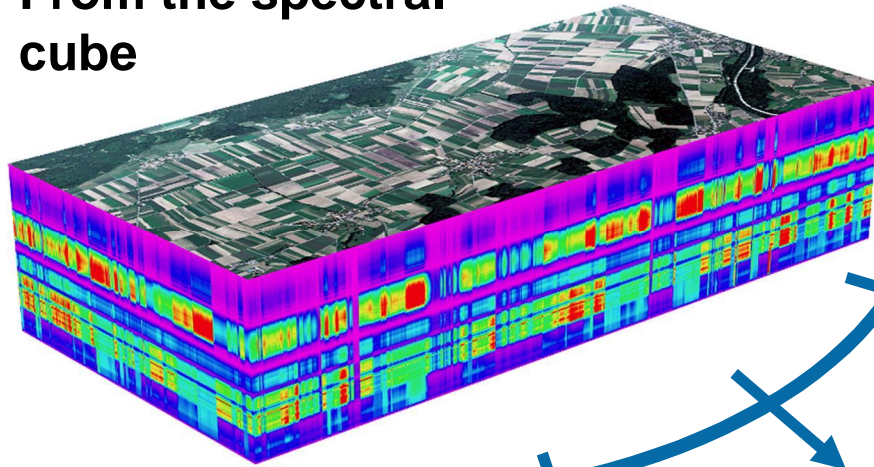


What: “data cube” w/100’s of bands



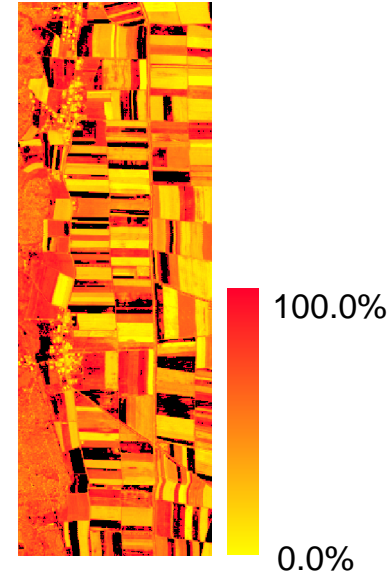
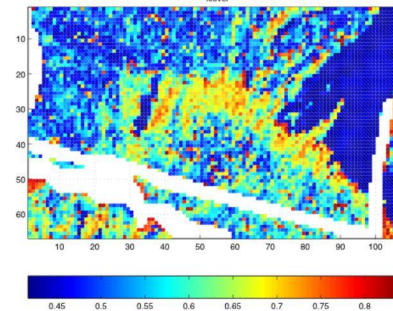
Why: imaging spectroscopy applications

From the spectral
cube

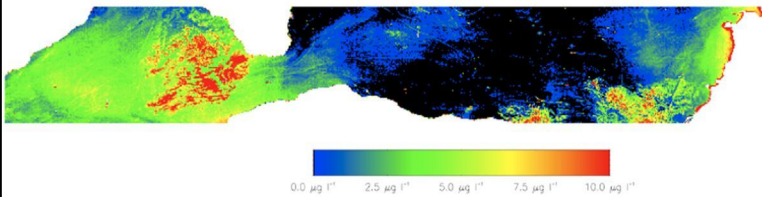


Precision Farming

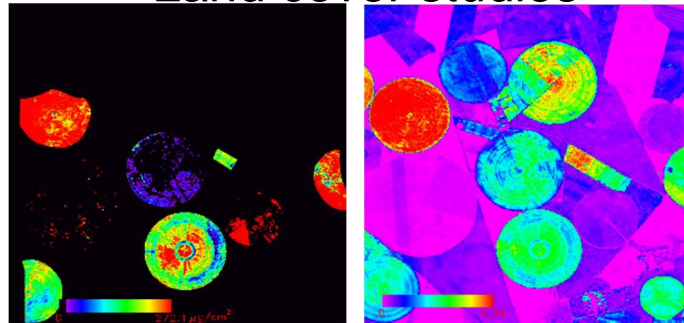
Forest Fire Modeling



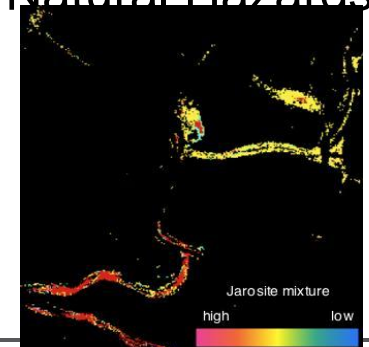
Water Quality



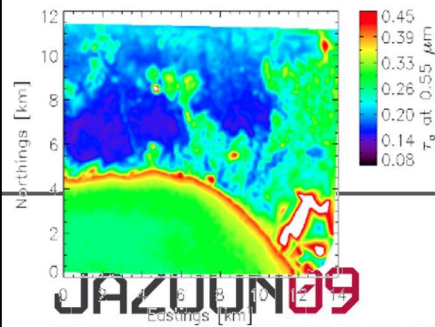
Land cover studies



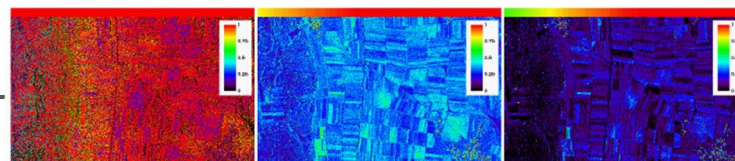
Natural Hazards



Air Pollution



Security relevant analysis



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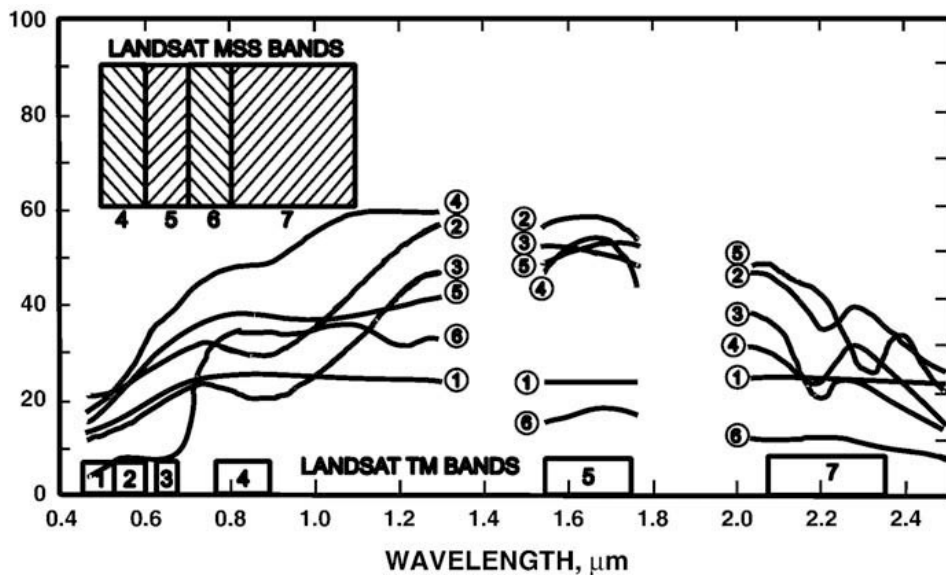
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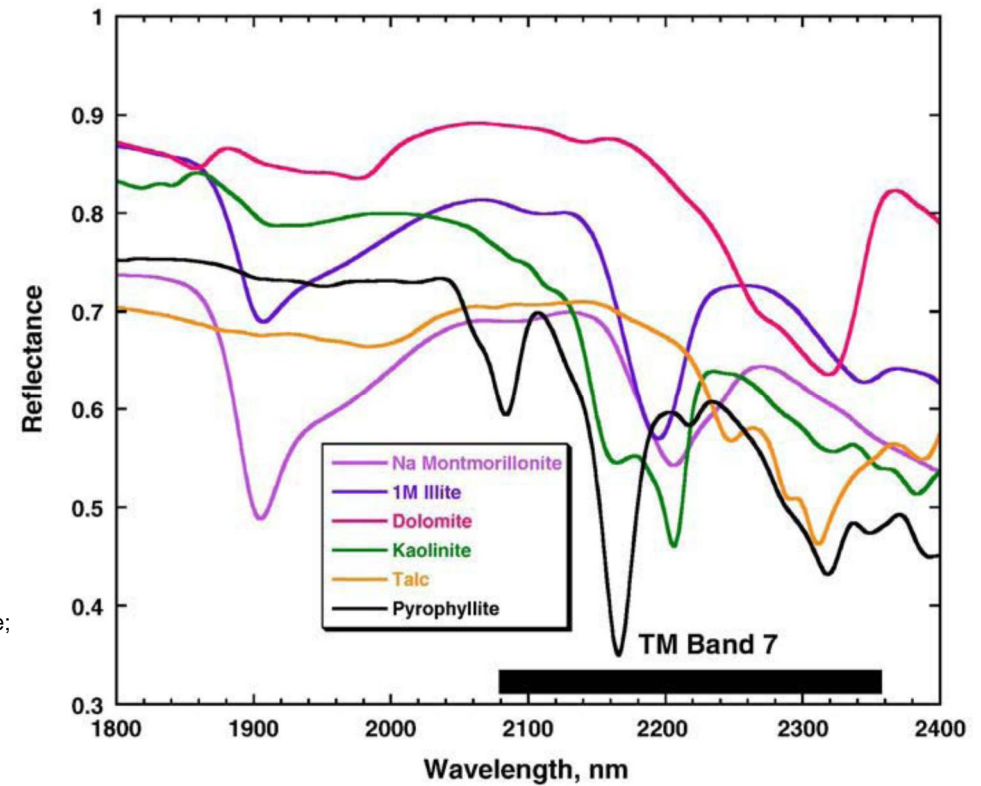
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Why: 100s of bands? Isn't ~10 enough?



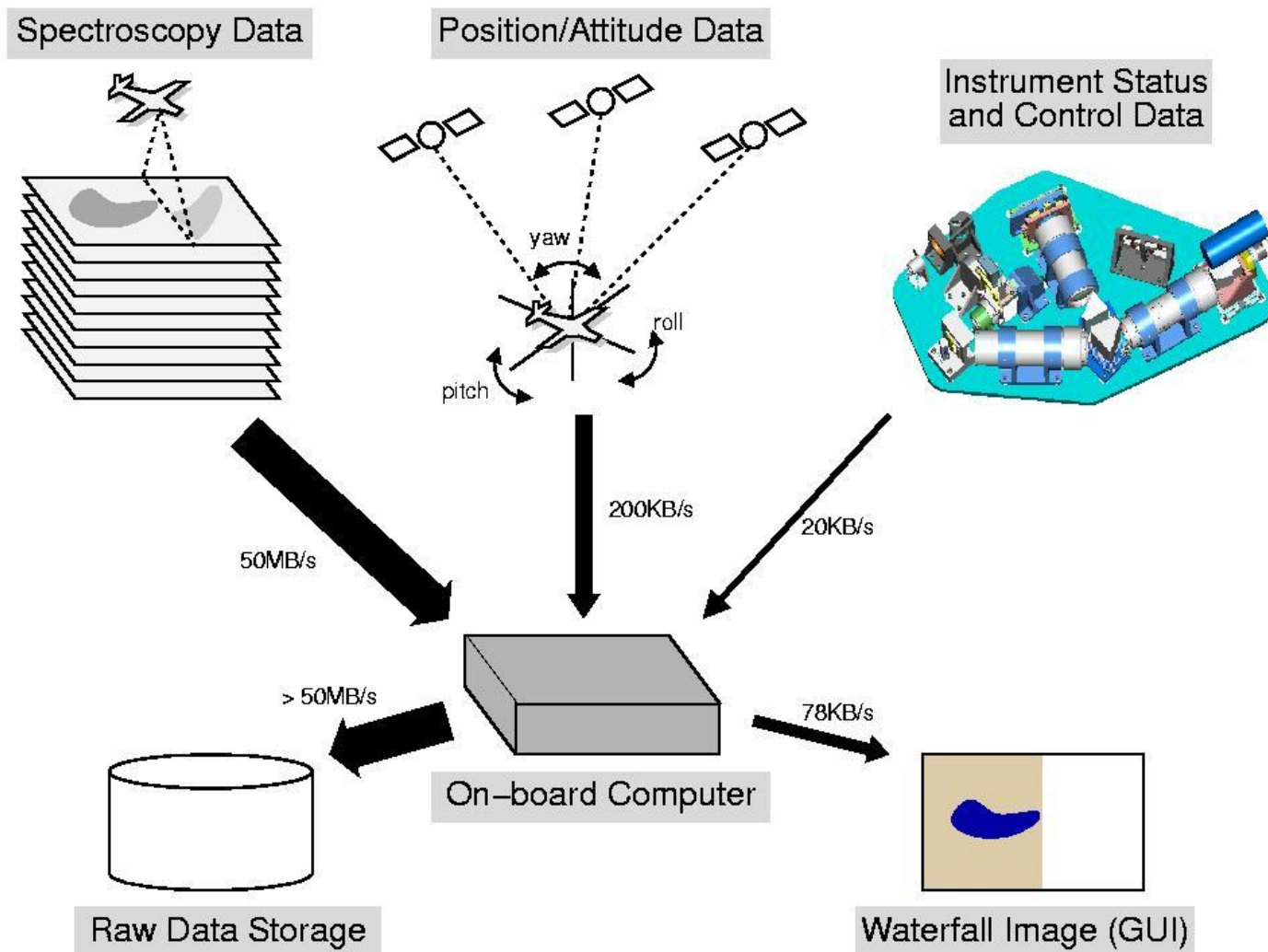
1) basalt; 2) hematite coating and montmorillonite; 3) hematite coating and alunite; 4) kaolinite; 5) dolomite; 6) vegetation. (Courtesy of NASA/JPL)



7 bands (Landsat) not detailed enough!

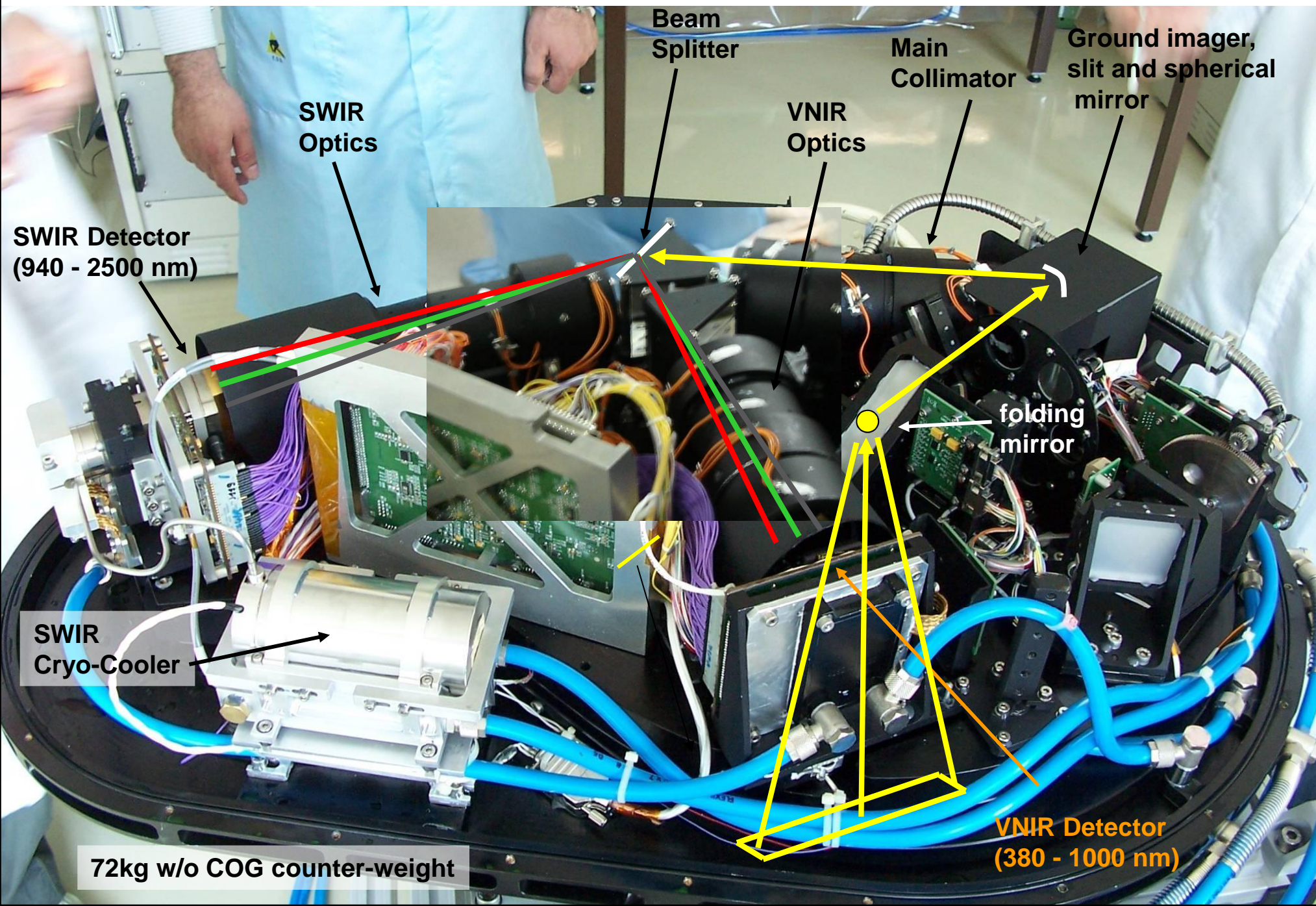
Goetz, A. F. H., Three decades of hyperspectral remote sensing of the Earth, Remote Sensing of Environment (2009), doi:10.1016/j.rse.2007.12.014

How: airborne data acquisition



How: the optical sub-unit

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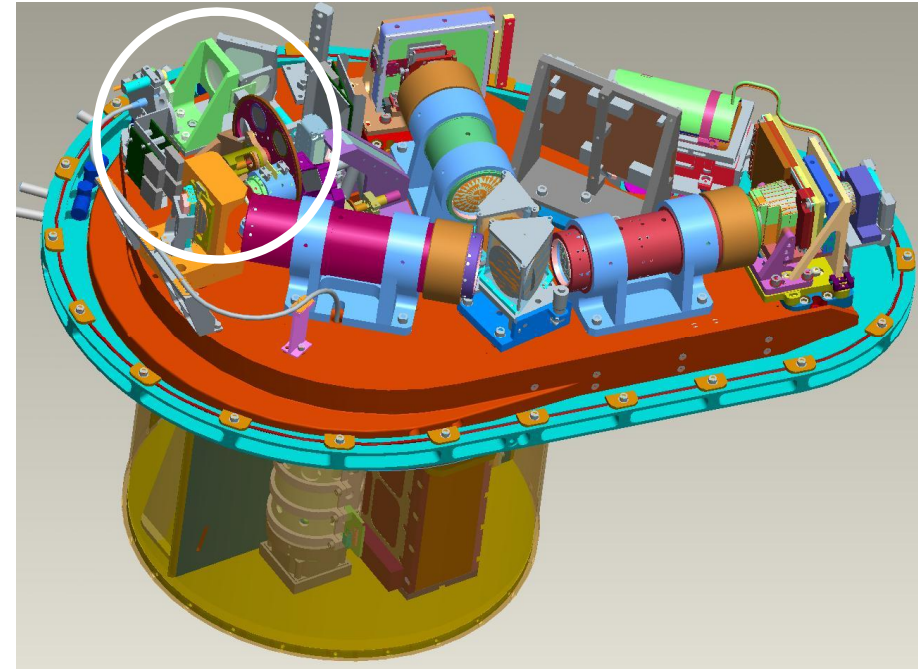
How: the in-flight characterization facility

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The **IFC** is a tool designed to **investigate** the overall instrument (radiometric, spectral, geometric) **stability** during the flight

Stabilised
IFC QTH lamp

Entrance
Baffle



Spectrometer
optical path

Filter
wheel

IFC
light path
(glass fiber)

Shutter for standard
imaging operations

Available Filters on the filter wheel:

- 3 Bandpass (color) Filters
- 1 Rare Earth Material (NIST) filter
- 1 Neutral Density (gray) filter

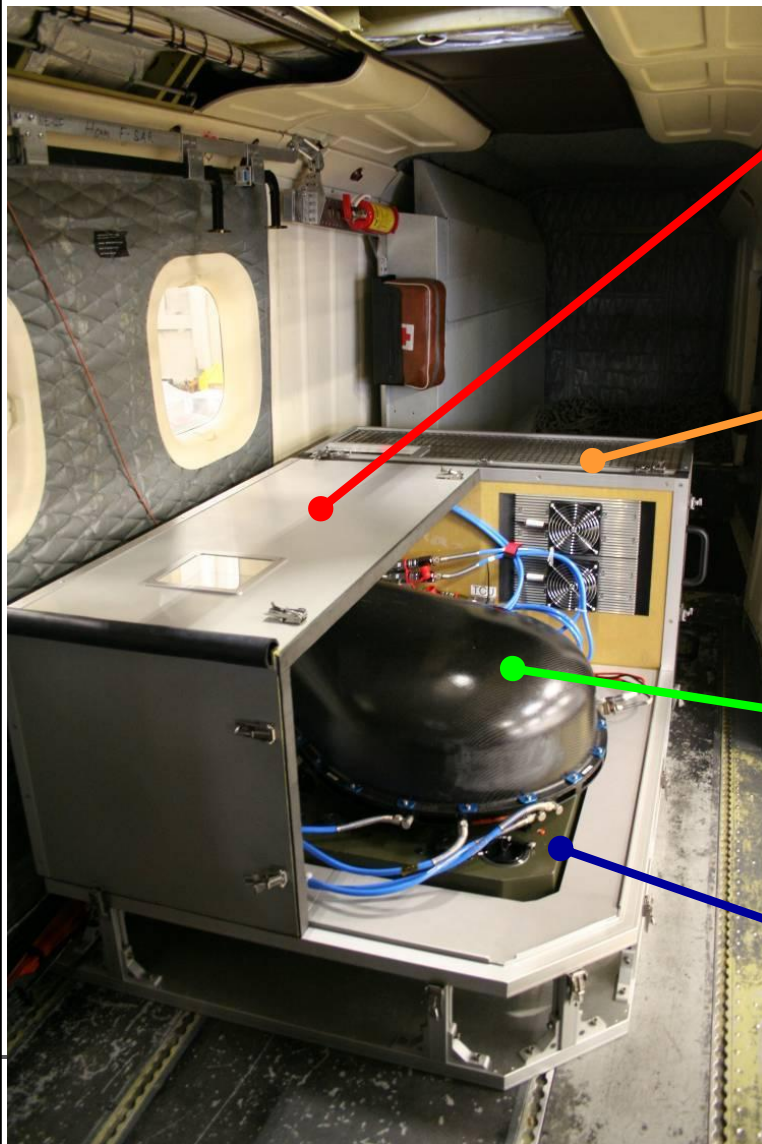
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How: instrument deployment (DO-228)

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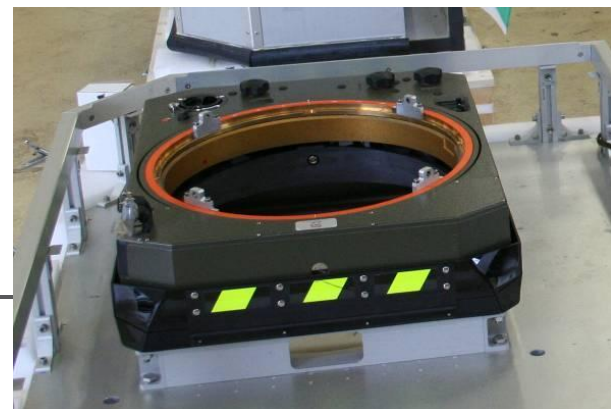
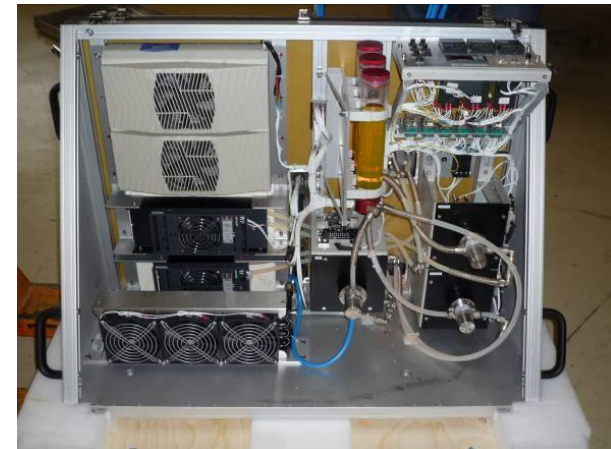
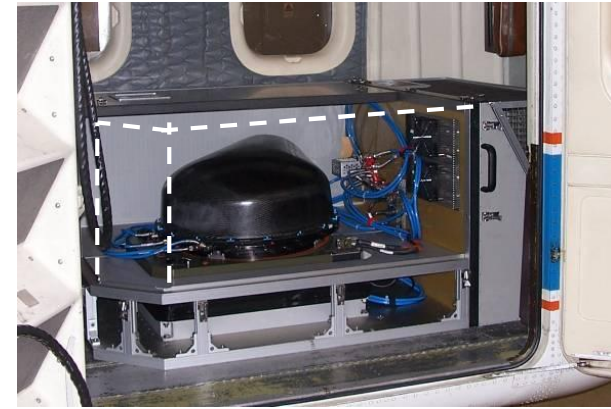


Environmental Thermal Control (ETC) Box

Thermal Control Unit (TCU)

Optical Subsystem Unit (OSU)

Stabilising Platform (Leica Pav30)

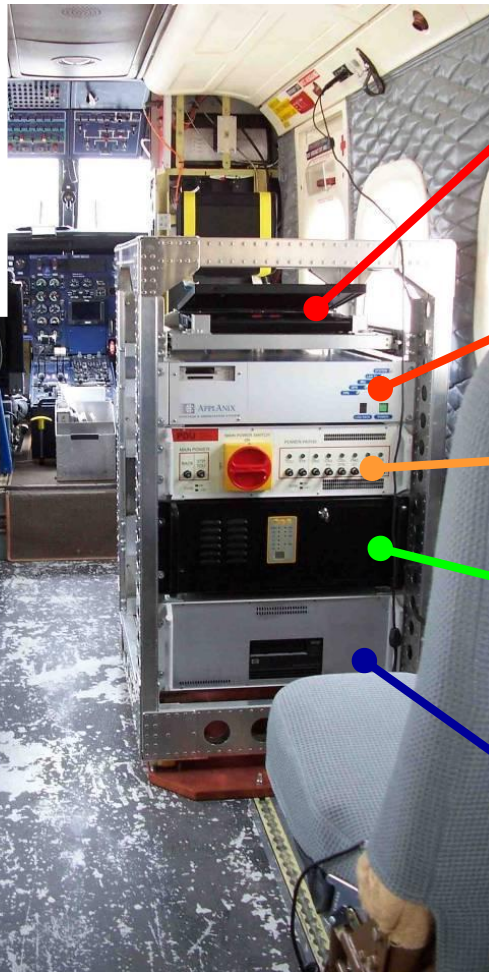


How: electronics deployment (DO-228)

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Operator rack workstation
for flight operations



On laptop:

- Operator's interface
- Flight Management System (FMS) (Track'Air)

Navigation sub-system
(Applanix POS/AV)

Power Distribution

Main control
computer (CSU)

Storage Unit (Solid State
Disks and tape)

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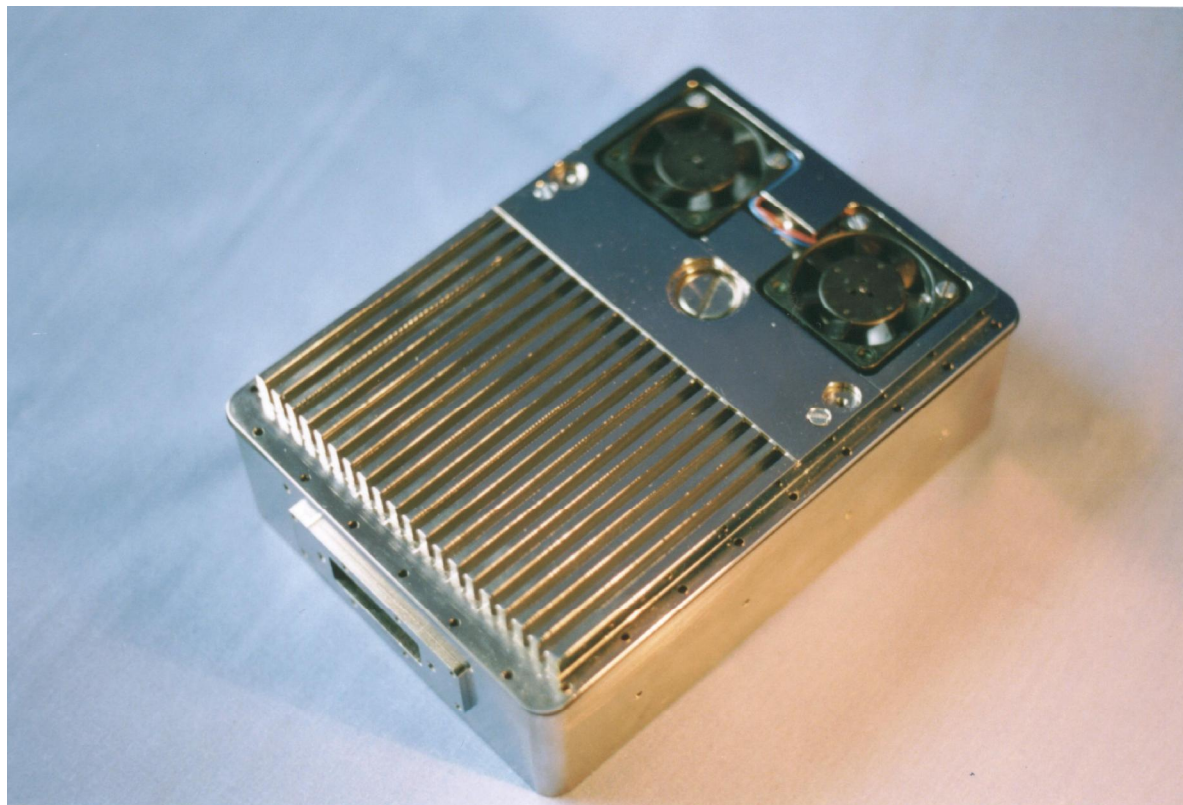


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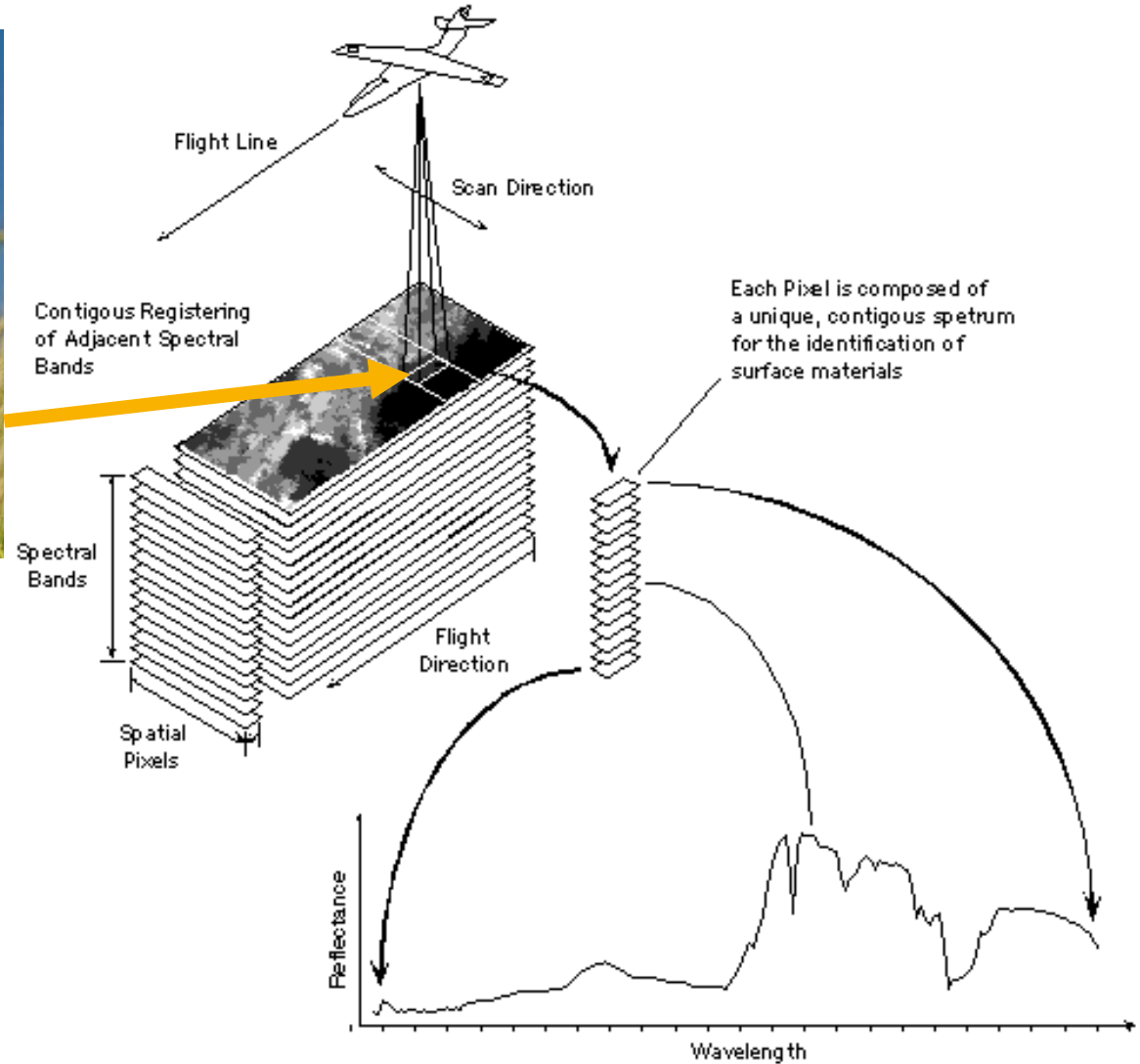
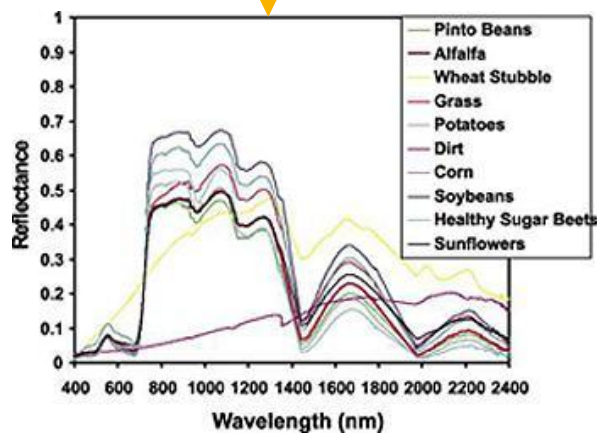
Aside: Originally, array of sealed hard drives



Consumer
Hard-drives
don't work at
high altitude

We've since
moved on to
SSD tech...

How: remotely + ground-sensed spectroscopy



Remote Sensing Tutorial, Nicholas M. Short, Sr.

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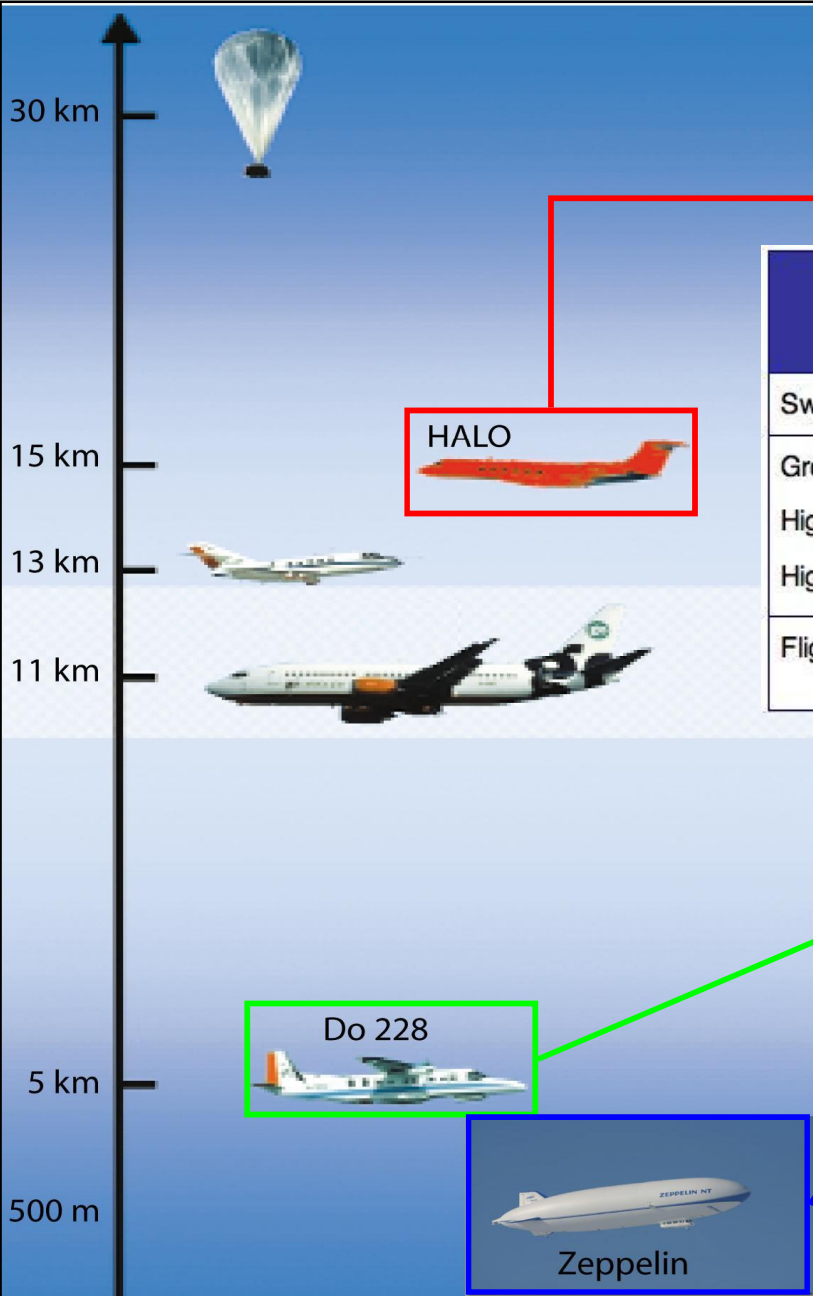
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How remote?

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Observation parameter	Zeppelin (H~ 500 m)	DO-228 (H< 5000 m)	HALO (H~ 14000 m)	Platform independent specification
Swath	0.25 km	< 2.5 km	8 km	FOV = 28 deg
Ground pixel size				IFOV = 0.028 deg
High spatial mode	0.25 m	< 2.5 m	8 m	~ 300 bands
High spectral mode	0.4 m	< 4 m	15 m	~ 500 bands
Flight line length	100 km	< 250 km	700 km	~ 60 min with standard hard disk array

April 2008: DLR Do228 Air Worthiness Certification

October 2008: 1st test flight (DLR Do228)

End 2009: DLR HALO Air Worthiness Certification

[Other platforms under evaluation]

Selected Software

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Aside: Real-Time Java (JSR-001, JSR-282)

- > Java RTS is Sun's implementation of JSR-001 (Final Release 3 – Jul 2006)
 - Real-Time Threads, Scheduling, and Synchronization
 - Avoiding Garbage Collection via Immortal and/or Scoped memory
 - Asynchronous handling of jvm-external events
 - ATC (one thread can “throw exception” in another)
 - Time and Timers
 - Direct access to physical memory

- > Also: JSR-282 “to fill in some minor gaps” (Early Draft Review – May 2009)

"the ability to reliably and predictably respond to a real-world event"

Aside: Real-Time Java (not used in APEX)

> Standard Java

```
while (true) do {  
    acquire_data();  
    now = System.currentTimeMillis()  
    Thread.sleep(next_period - now);  
    send_data();  
    next_period += period;  
}
```

> Real-Time Java

```
setPriority(my_RTPriority);  
setReleaseParameters(myPeriodParam);  
while (true) do {  
    acquire_data();  
    RealtimeThread.waitForNextPeriod();  
    send_data();  
}
```

e.g. Real-Time Java's **RealtimeThread** + **RawMemoryAccess** *could* be used to implement APEX's current producer/consumer acquisition logic

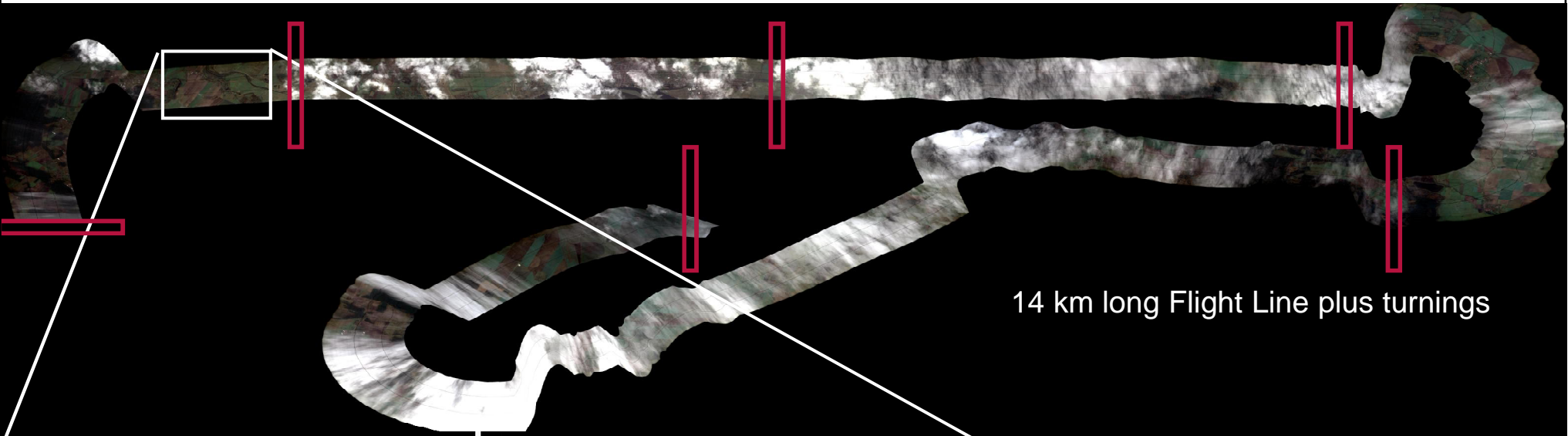
Code adapted from Bertrand Delsart, Real-Time Java for Latency Critical Banking Applications

Selected APEX Software

- > Data Acquisition/Control/Monitoring (some examples)
 - Flight plan triggered camera control
 - Multi-sensor data (w/temporal synchronization)
 - Imagery
 - Positional
 - Calibration
 - Environmental
 - Near real-time “waterfall image” monitoring
- > Offline Processing (some examples)
 - Instrument calibration support (Seasonal)
 - Radiometric/spatial correction (Per campaign)
 - Parametric ortho-rectification (Per campaign)
 - Atmospheric correction (Per campaign)

Acq: Flight-plan triggered camera control

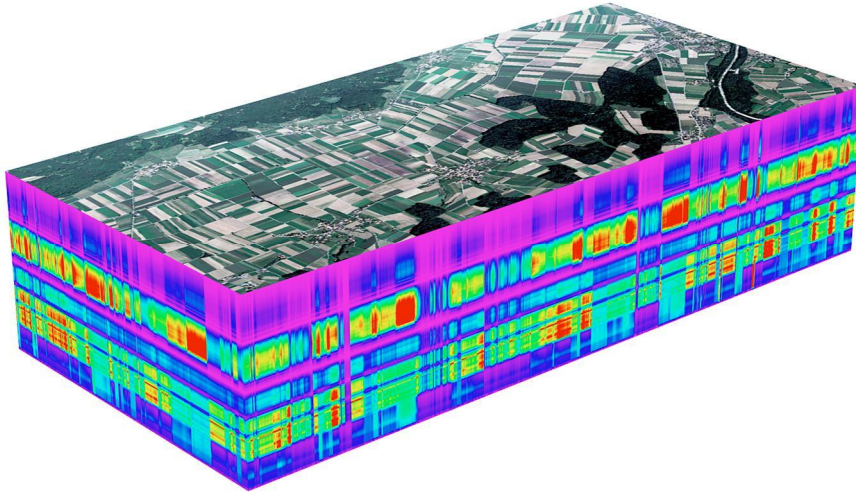
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14 km long Flight Line plus turnings



Aside: options for 3-D Data Arrangement



	-----1 to n columns----- -----1 to n columns----- -----1 to n columns-----		
Row 1	Band 1	Band 2	Band 3
Row 2	Band 1	Band 2	Band 3
Row n	Band 1	Band 2	Band 3

Band interleaved by Line (BIL) - compromise

	Pixel (1,1)			Pixel (1,2)				Pixel (1,n)		
Row 1	Band 1	Band 2	Band 3	Band 1	Band 2	Band 3		Band 1	Band 2	Band 3
Row n	Band 1	Band 2	Band 3	Band 1	Band 2	Band 3		Band 1	Band 2	Band 3
	-----1 to n columns-----									

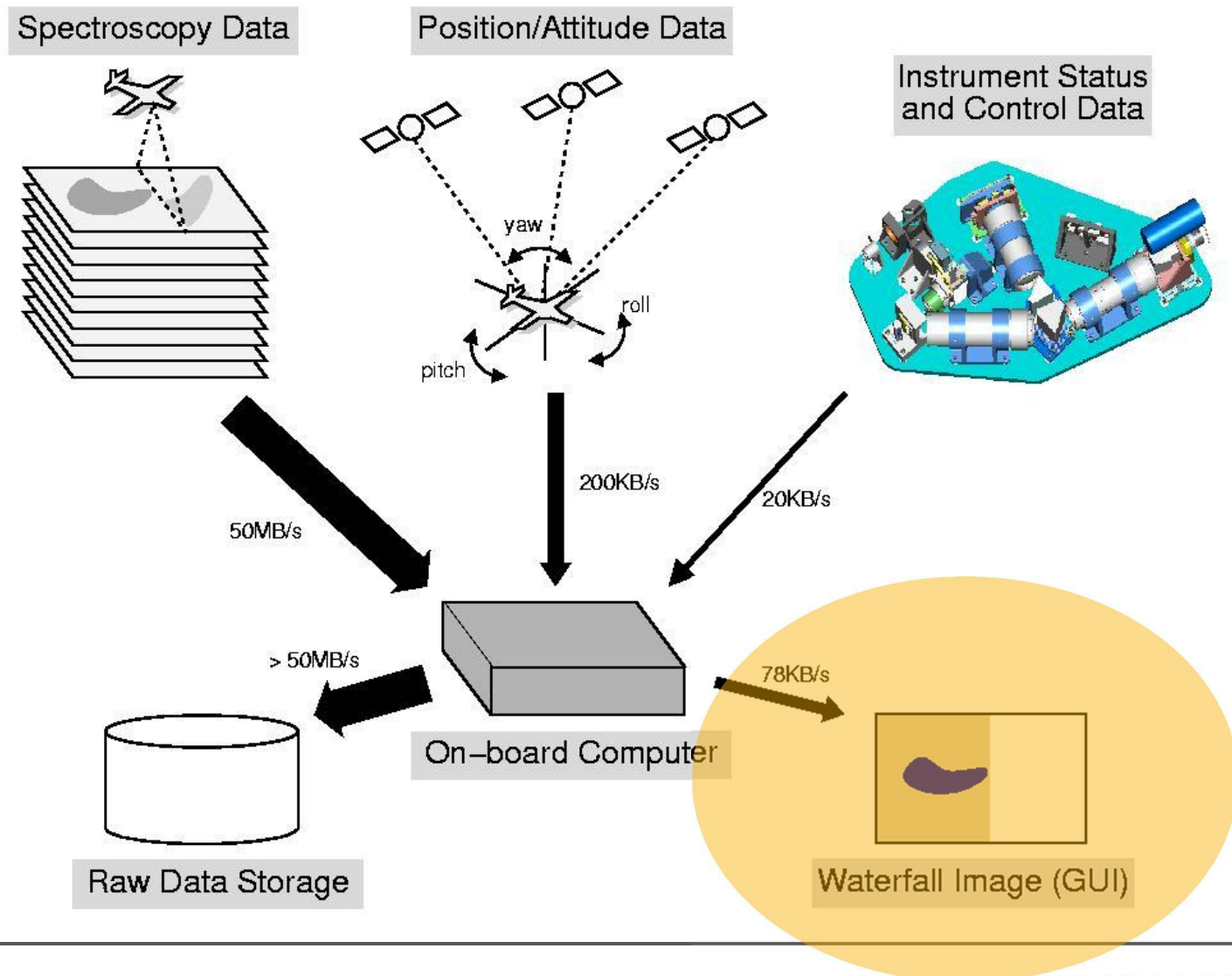
Band interleaved by Pixel (BIP) - spectral

	-----1 to n columns-----		
Rows 1 .. n	Band 1		
Rows 1 .. n	Band n		

Band Sequential (BSQ) - spatial

Figures, Phil Hurvitz, U. Washington

Acq: waterfall image viewer



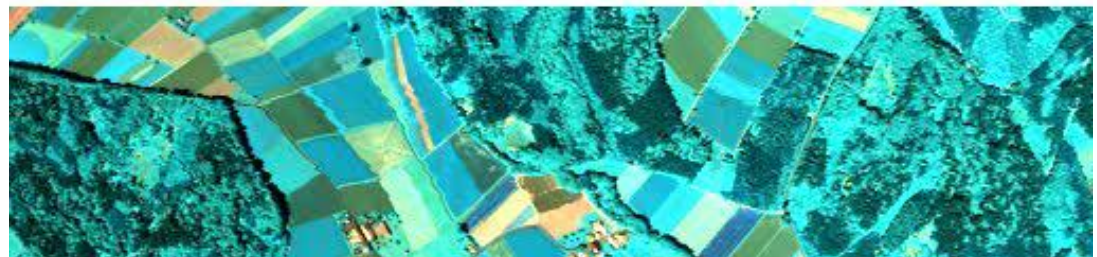
Acq: waterfall image viewer

> What?

- A “false color” line-by-line preview of incoming data...

> Why?

- Verify proper “operation mode” – calibration vs acquisition
- Verify “frame-rate/integration time settings”...
- Verify “band settings/groupings” for this application...
- Verify pilot’s flight path is as expected...



“did we remove the lens cap?”
“do we have the right ‘shutter’ speed?”
“is the subject within the frame?”

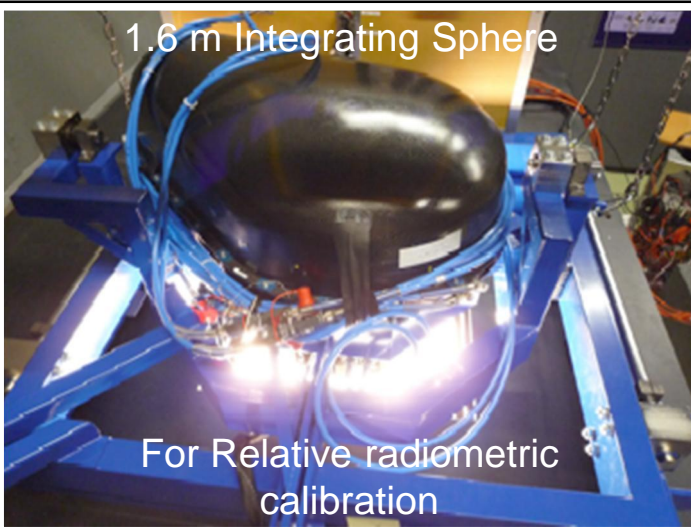
Aside: queuing theory issues and near-real time

```
DatagramPacket dgram = new DatagramPacket(new byte[msgsize], msgsize);
while (isrunning && udpsock != null) {
    try {
        udpsock.receive(dgram);
        if (dgram.getLength() == msgsize) {
            dataProcessor.processData(dgram.getData());
        } else {
            LOGGER.error("Bad packet, len = " + (dgram.getLength()));
        }
    } catch (java.net.SocketTimeoutException e) {
        LOGGER.info("No lines received for " + timeoutms + " ms");
        dataProcessor.repaint();
        // expect to sometime receive nothing...
    } catch (java.io.IOException e) {
        LOGGER.error("udp receive error!");
    }
}
```

UDP – expect dropped packets and data underflow or overflow.

Server logic tries to keep waterfall buffer 20-80% full for handling bursts and variable frame rates.

1.6 m Integrating Sphere



For Relative radiometric calibration

Offline: Seasonal Calibration (CHB@DLR Munich)*

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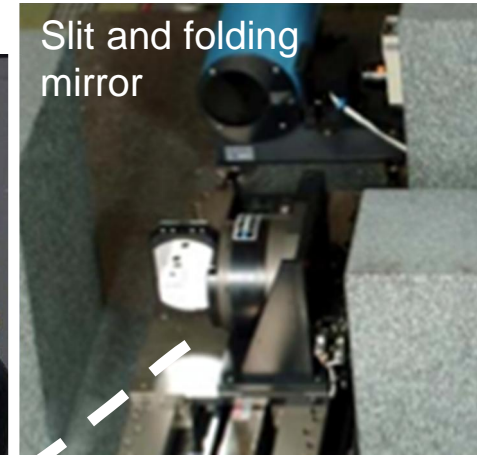
* Under ESA-EOP Contract
Status: Acceptance review successful
Jan 2007

0.5 m Integrating Sphere

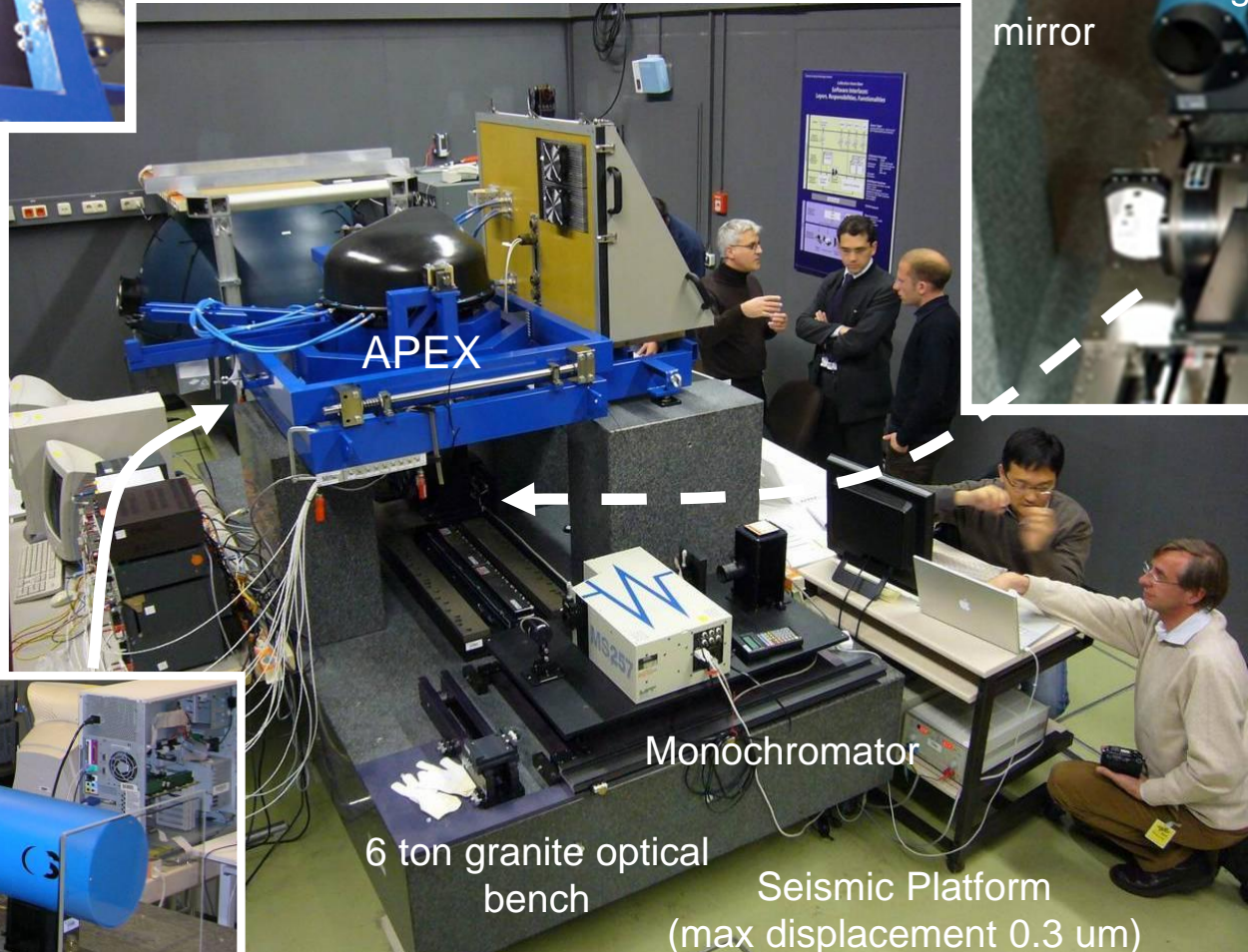


For Absolute radiometric calibration

Slit and folding mirror



APEX

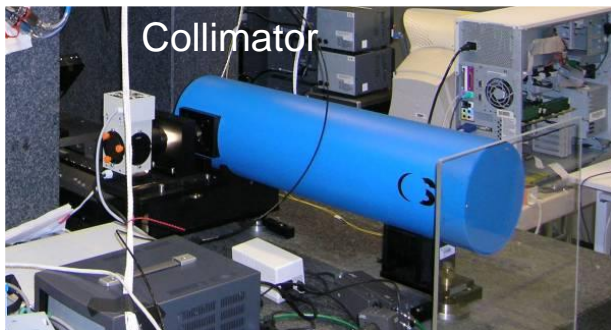


Monochromator

6 ton granite optical bench

Seismic Platform
(max displacement 0.3 um)

Collimator



JAZO

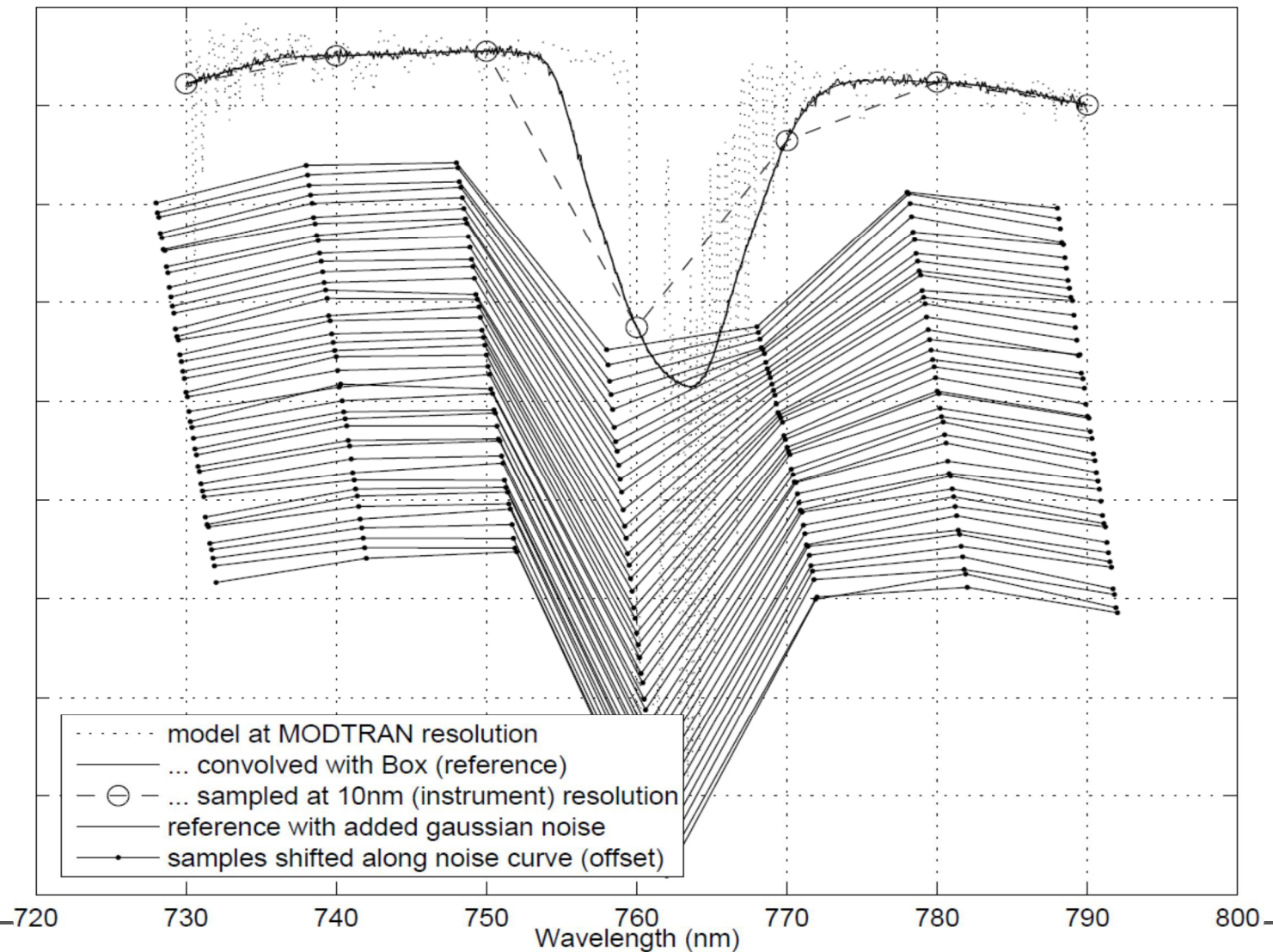
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Offline: Image feature-based calibration

Well-known
Fraunhofer line “A”
(due to
atmospheric
oxygen) used to
calibrate potential
instrument band
center shifts



Offline: Radiometric calibration

Converting
recorded *digital
numbers* to
physical
parameters in
*calibrated
radiance* units



Illustration, CRIM - Centre de recherche informatique de Montréal

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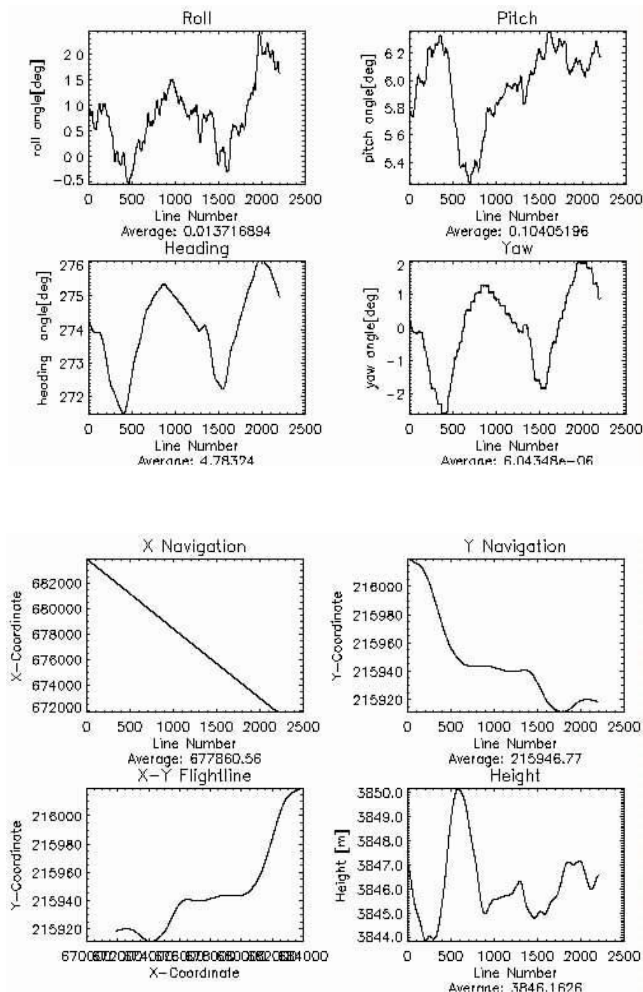
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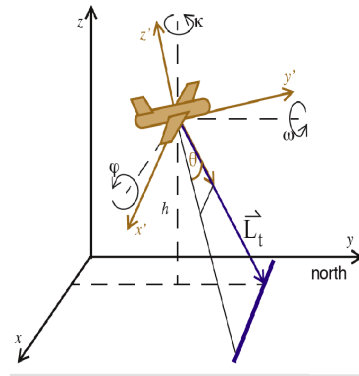
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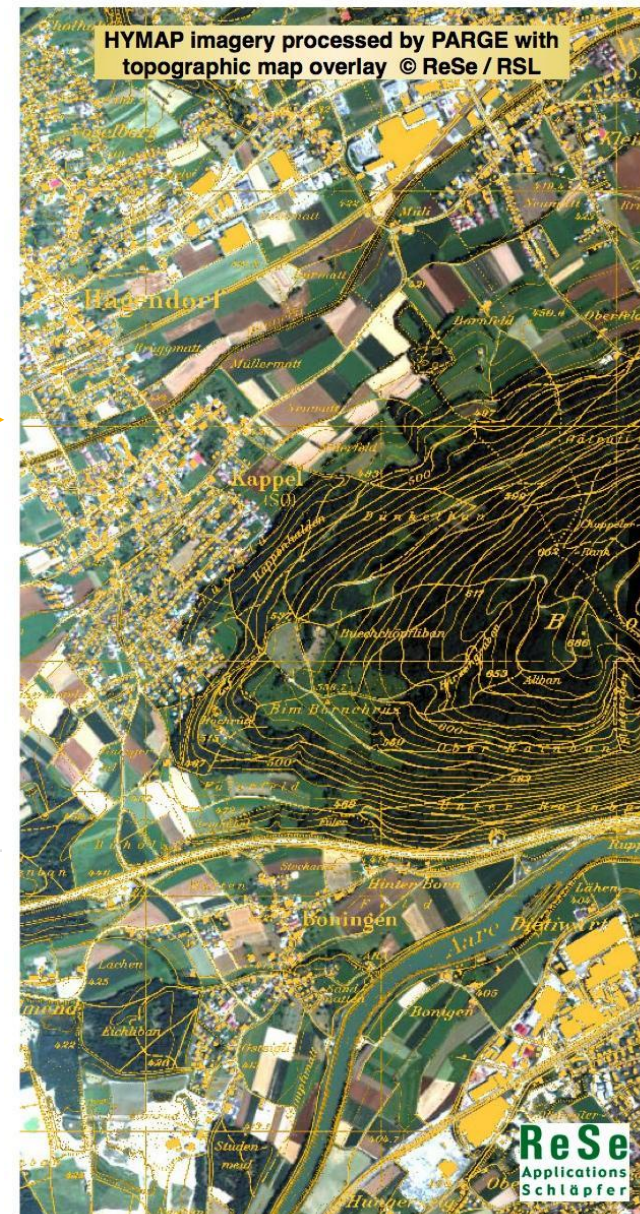
Offline: Orthorectification



attitude



GPS



Offline: ATCOR - Atmospheric Correction

Using radiative transfer algorithms based on atmospheric optical properties to derive surface reflectance by inversion



Image: Satellite Imaging Corporation, satimagingcorp.com

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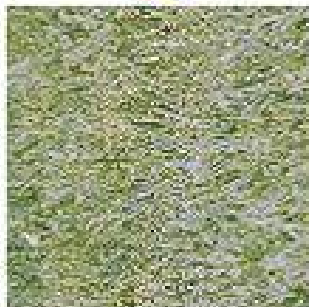
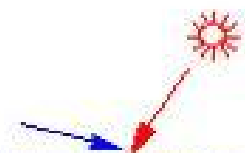
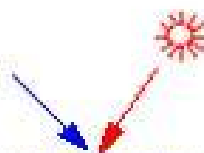
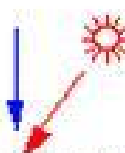
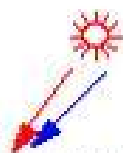
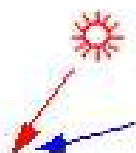
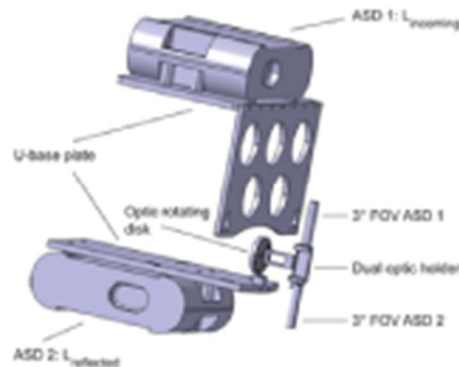
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Offline: BRDF Correction



+75°
(backscatter)

+45°
(backscatter)

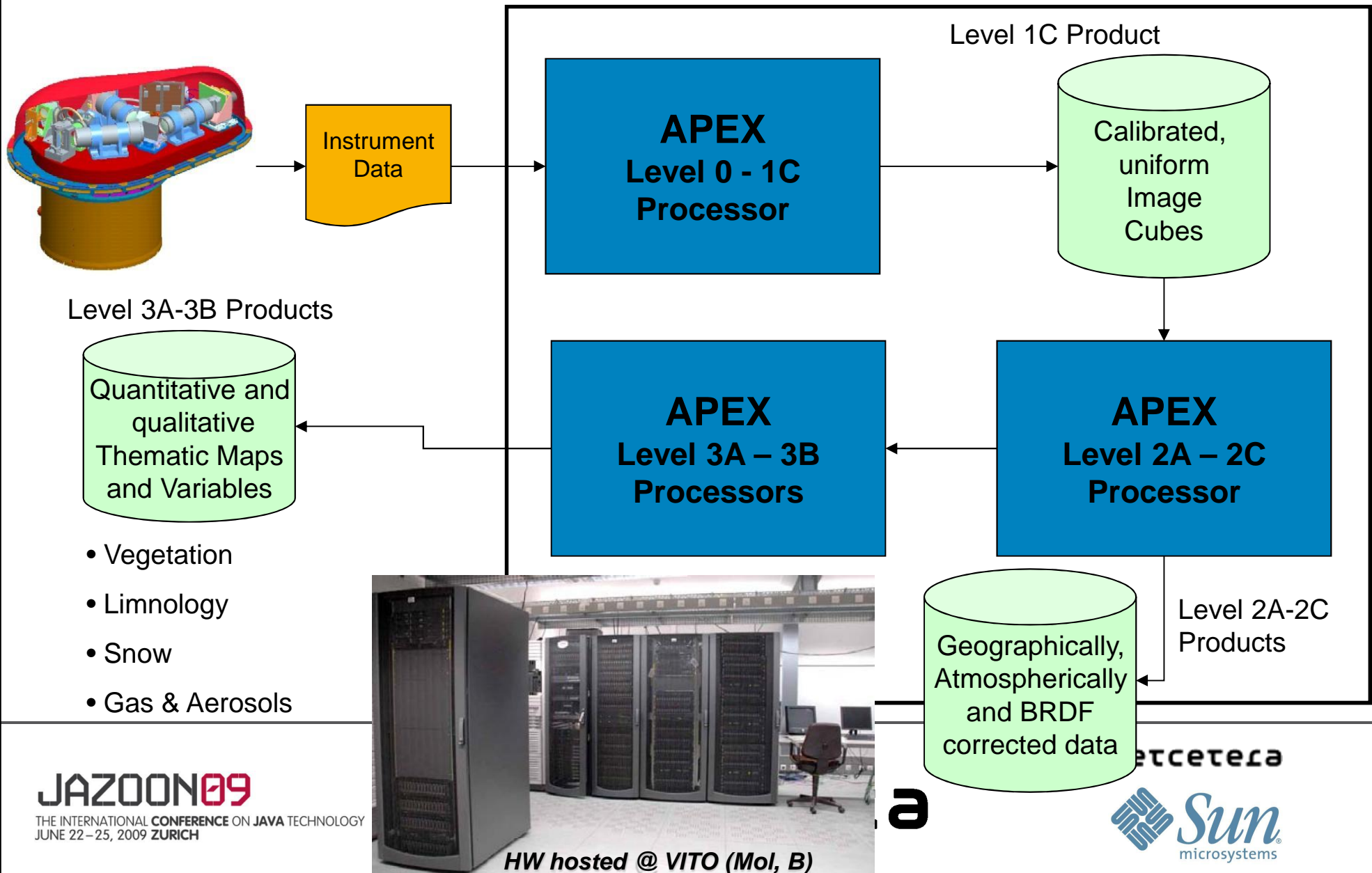
0° (nadir)

-45° (forward
scatter)

-75° (forward
scatter)

BRDF effects can be seen as stripes in freshly mowed grass

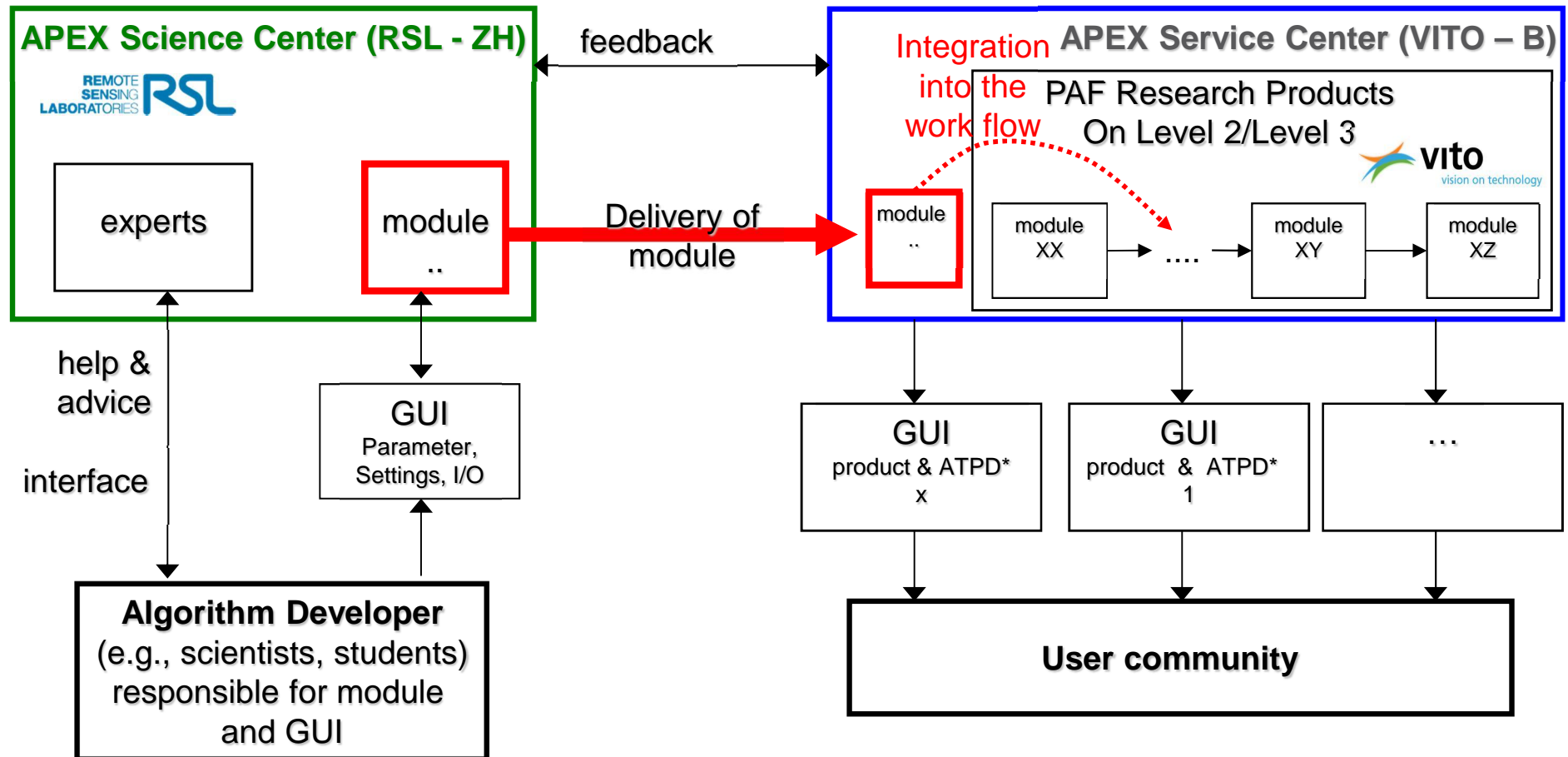
Offline: Product Generation



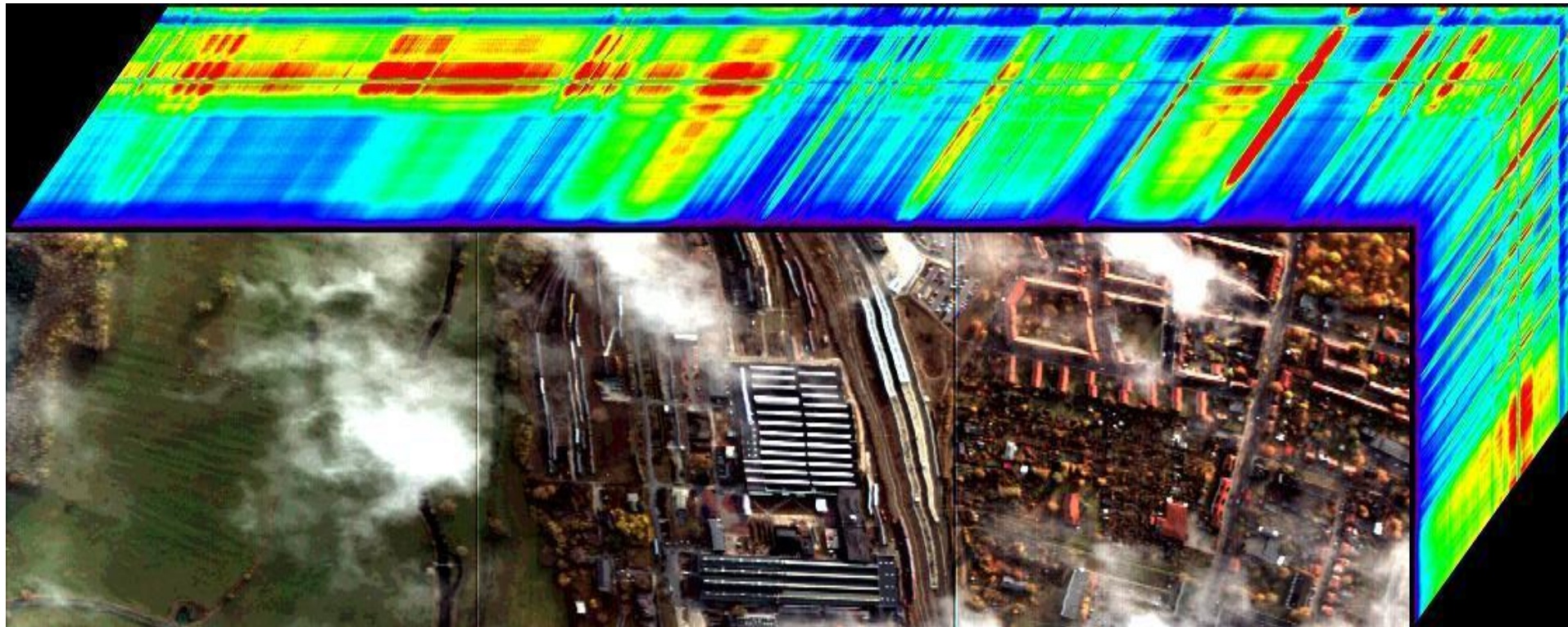
Offline: Do-it-yourself Module/Algorithm dev?

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Can integrate customized processing module at any point of the processing chain.



Test Flight over Wittenberge (D), 31/10/2008



1st Radiometrically Calibrated APEX Cube

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Mission Status/Timeline

